$\mathbf{S} = (\mathcal{D}, \geq, \mathbf{Q}, \geq^*, \mathbf{T}, \mathbf{V}, \mathbf{F})$

- ≥ preference on document representations
- \geq * preference on query representation
- (\mathcal{D}, \geq) defines the document space
- (\mathcal{D}, \geq^*) defines the query space

ALL IN THE CONTEXT OF ONE USER NEED

Learning in Vector Model using Relevance Feedback Optimal Ouery Formulation

$$\underline{\mathbf{q}} = (\underline{\mathbf{q}}_{1}, \underline{\mathbf{q}}, \dots \underline{\mathbf{q}}_{n})$$

$$\underline{\mathbf{d}}_{\alpha} = (W_{\alpha 1}, W_{\alpha 2}, \dots W_{\alpha n})$$
choose $\underline{\mathbf{q}}$ s.t.
$$\underline{\mathbf{d}}_{\alpha} = \underbrace{\mathbf{q}^{\mathrm{T}}}_{\mathbf{q}} = \underbrace{\begin{cases} \succeq 0, \text{if } \underline{d}_{\alpha} \in REL \\ \prec 0, \text{if } \underline{d}_{\alpha} \in NREL \end{cases}}_{\text{for } \alpha = 1, 2, \dots, p}$$

In the following we apply the "conversion" operation for \underline{d}_{α} to get $\frac{\Lambda}{\underline{d}_{\alpha}}$

Let
$$\hat{\underline{d}}_{\alpha} = \begin{cases} \underline{d}_{\alpha}, \text{if } \underline{d}_{\alpha} \in REL \\ -\underline{d}_{\alpha}, \text{if } \underline{d}_{\alpha} \in NREL \end{cases}$$

 $\hat{w} = \begin{pmatrix} \hat{\underline{d}}_{1} \\ \hat{\underline{d}}_{2} \\ \bullet \\ \bullet \\ \hat{\underline{d}}_{p} \end{pmatrix}$
 $\hat{\underline{U}} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$
 $\hat{W} \underline{q}^{T} \succ \underline{0}$
 \bullet Find the best possible a

- Find the best possible <u>q</u>
- Relevance feedback

PROBLEM STATEMENT

Find \underline{q} such that $J_p(\underline{q})$ is minimized Subject to

$$\underline{\hat{d}}_{\alpha}\underline{q}^{T} \succ 0$$

for all α

This is a system of linear in equalities



Figure 2.5. Geometrical illustration of the pattern space and the weight space.

(a) Pattern space. (b) Weight space



(1,1)(0,1)(1,0)(0,0) $REL \leftarrow \underline{d}_1$ $NREL \leftarrow \underline{d}_2$ $NREL \leftarrow \underline{d}_3$ NREL

 $\hat{d}_1 = (1,1,1)$ $\hat{d}_2 = (0,-1,-1)$ $\hat{d}_3 = (-1,0,-1)$ homogeneous coordinate representation

ITERATIVE (DESCENT)

PROCEDURES

- Instead of a "batch" approach, here we consider an iterative approach.

$$\underline{\mathbf{q}}^{(k+1)} = \underline{\mathbf{q}}^{(k)} - \rho_k \frac{\partial J(\underline{q})}{\partial \underline{q}} \Big| \underline{q} = \underline{q}^{(k)}$$

 ρ_k – grain factor of step (iteration) k Many forms of J(<u>q</u>) are possible. d_{α} is <u>misclassified</u> if $\hat{d}_{\alpha}\underline{q}^T \leq 0$

Let $y(\underline{q}) = \{ \underline{\hat{d}}_{\alpha} | \underline{\hat{d}}_{\alpha} \underline{q}^{T} \leq 0 \}$

Perception criterion Function $J_p(\underline{q}) = -\sum_{\hat{d}_{\alpha} \in \mathcal{Y}(\underline{q})} \hat{\underline{d}}_{\alpha} \underline{q}^T$

Taking a derivative of $J_p(\underline{q})$ with respect to \underline{q} yields: $\frac{\partial J_p(\underline{q})}{d\underline{q}} = -\sum_{\hat{d}_{\alpha} \in \mathcal{Y}(\underline{q})} \sum_{\hat{d}_{\alpha} \in \mathcal{Y}(\underline{q})} \sum_{$

We, therefore, adjust $\underline{\mathbf{q}}(\mathbf{k})$ by $-\sum_{\hat{\underline{d}}_{\alpha} \in y(\underline{q}^{k})} \hat{\underline{d}}_{\alpha} \in y(\underline{q}^{k})$ $\underline{\mathbf{q}}^{(k+1)} = \underline{\mathbf{q}}^{(k)} + \rho_{k} \sum_{\hat{\underline{d}}_{\alpha} \in y(q^{k})} \hat{\underline{d}}_{\alpha}$

$$\underline{q}^{(k+1)} = \underline{q}^{(k)} + \rho_k \underline{S}$$
where $\underline{S} = \{ \underline{0}, ifd_{\alpha}is \\ \underline{\hat{d}}_{\alpha}, otherwise}$ correctly classified

-- learning is by sample $0 < \rho_k \le 1$

 $\frac{\text{PERCEPTRON CRITERION}}{J_{p}(\underline{q}) = \sum_{\underline{\hat{d}} \in y(\underline{q})} \underline{\hat{d}} \underline{q}^{T}}$

where y(q) is the set of training vectors <u>misclassified</u> by q

Training by Epoch <u>PERCEPTRON CONVERGENCE</u> <u>ALGORITHM (PCA)</u>

- ⁽¹⁾ k=0; Choose initial query vector \underline{q}^0
- (2) Determine $y(\underline{q}^k)$
- (3) If $y(\underline{q}^k) = \phi$, terminate

(4)
$$\underline{\mathbf{q}}^{k+1} = \underline{\mathbf{q}}^{k} + \rho_k \underbrace{\sum \hat{\underline{d}}}_{\hat{\underline{d}} \in \mathcal{Y}(\underline{q}_k)}$$

(5)
$$k = k+1$$
, go to step (2)

linearizability

Theorem: PCA will terminate if linearizability property holds for the training data. EX. d = (1, 1, 0, 1, 1) NDEL

$$\underline{d}_{1} = (1,1,0,1,1) \} \text{ NREL}$$

$$\underline{d}_{2} = (1,0,1,0,1)$$

$$\underline{d}_{3} = (0,1,1,0,1) \}^{REL}$$

$$\underline{d}_{4} = (0,1,0,1,1) \} \text{ NREL}$$

$$\frac{\hat{d}_1}{\hat{d}_2} = (-1, -1, 0, -1)$$

$$\frac{\hat{d}_2}{\hat{d}_2} = (1, 0, 1, 0, 1)$$

$$\frac{\hat{d}_3}{\hat{d}_4} = (0, -1, 0, -1)$$

 $\underline{q}^{0} = (0, 0, 0, 0, 0)$ $y(\underline{q}^0) = (all of them)$ $\underline{q}^{1} = (0, -1, 2, -2, 0)$ let $\rho_k = 1$ $y(q^1) = \phi$

$\underline{q}^{opt} = (0, -1, 2, -2, 0)$